

**A COMMON FIXED POINT THEOREM FOR A FAMILY OF  
SELMAPPINGS SATISFYING A GENERAL CONTRACTIVE  
CONDITION OF OPERATOR TYPE**

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ABSTRACT. In this paper, we prove a common fixed point theorem for a family of selfmappings satisfying a general contractive condition of operator type.

1. INTRODUCTION

The class of generalized contraction mappings, introduced and studied by Ćirić in [6], is very significant in a fixed point theory. As noted by Gornićki and Rhoades [8], a contractive condition (2.1) on a pair of generalized contractions. Jungck [9] proved a fixed point theorem for commuting maps generalizing the Banach's fixed point and further he [10] introduced more generalizing commutativity, so called compatibility, which is more general than that of weak commutativity defined by Sessa [12]. Lately, Branciari [4] obtained a fixed point results for a single mapping satisfying an analogue of Banach's contraction principle (see [3] and [5]) for an integral type inequality. Rhoades [11] proved two fixed point theorems involving more general contractive conditions. Vijayaraju et al. [13] established a general principle, which made it possible to proved many fixed point theorems for a pair of maps of integral type. Aliouche [1] gave a common fixed point theorem for selfmappings of a symmetric space under a contractive condition of integral type. Altun and Turkoglu [2] proved a fixed point theorem for mappings satisfying a general contractive of operator type.

The main purpose of this paper is to give a common fixed point theorem for a family of selfmappings satisfying a general contractive condition of operator type.

2. PRELIMINARIES

Let  $X$  be a nonempty set and let  $\{T_\alpha\}_{\alpha \in J}$  be a family of selfmappings on  $X$  and  $J$  indexing set. A point  $u \in X$  is called a common fixed point for a family

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2000 *Mathematics Subject Classification.* 47H10, 54E50, 58J20.

*Key words and phrases.* Common fixed point, contractive condition of operator type.

$\{T_\alpha\}_{\alpha \in J}$  iff for each  $T_\alpha$ . The following theorem was given by Ćirić [7] for a family of generalized contraction.

**Theorem 1.** *Let  $(X, d)$  be a complete metric space and let  $\{T_\alpha\}_{\alpha \in J}$  be a family of selfmappings of  $X$ . If there exists fixed  $\beta \in J$  such that for each  $\alpha \in J$ :*

$$(2.1) \quad d(T_\alpha x, T_\beta y) \leq \lambda \max \left\{ \begin{array}{l} d(x, y), d(x, T_\alpha x), d(y, T_\beta y), \\ \frac{1}{2} [d(x, T_\beta y) + d(y, T_\alpha x)] \end{array} \right\}$$

for some  $\lambda = \lambda(\alpha) \in (0, 1)$  and all  $x, y \in X$ , then all  $T_\alpha$  have a unique common fixed point, which is a unique fixed point of each  $T_\alpha$ ,  $\alpha \in J$ .

The following theorem was given by Branciari [4] was to analyze the existence of fixed points for mappings of  $f$  defined on a complete metric space  $(X, d)$  satisfying a contractive condition of integral type.

**Theorem 2.** *Let  $(X, d)$  be a complete metric space,  $c \in (0, 1)$  and  $f : X \rightarrow X$  be a mapping such that for each  $x, y \in X$  one has*

$$\int_0^{d(fx, fy)} \varphi(t) dt \leq c \int_0^{d(x, y)} \varphi(t) dt$$

where  $\varphi : [0, +\infty) \rightarrow [0, +\infty)$  is a Lebesgue-integrable mapping which is summable (i.e. with finite integral) on each compact subset of  $[0, +\infty)$ , non-negative and such that for each  $\varepsilon > 0$ ,  $\int_0^\varepsilon \varphi(t) dt > 0$ ; then  $f$  has a unique fixed point  $a \in X$  such that for each  $x \in X$ ,  $\lim_{n \rightarrow \infty} f^n x = a$ .

The following concept of  $O(f; \cdot)$  and its examples was given by Altun and Turkoglu [2].

Let  $F([0, \infty))$  be class of all function  $f : [0, \infty) \rightarrow [0, \infty]$  and let  $\Theta$  be class of all operators

$$O(\bullet; \cdot) : F([0, \infty)) \rightarrow F([0, \infty)), \quad f \rightarrow O(f; \cdot)$$

satisfying the following conditions:

- (i)  $O(f; t) > 0$  for  $t > 0$  and  $O(f; 0) = 0$ ,
- (ii)  $O(f; t) \leq O(f; s)$  for  $t \leq s$ ,
- (iii)  $\lim_{n \rightarrow \infty} O(f; t_n) = O(f; \lim_{n \rightarrow \infty} t_n)$ ,
- (iv)  $O(f; \max\{t, s\}) = \max\{O(f; t), O(f; s)\}$  for some  $f \in F([0, \infty))$ .

**Example 1.** *If  $f : [0, \infty) \rightarrow [0, \infty)$  is a Lebesgue integrable mapping which is finite integral on each compact subset of  $[0, \infty)$ , non-negative and such that for each  $t > 0$ ,  $\int_0^t f(s) ds > 0$ , then the operator defined by*

$$O(f; t) = \int_0^t f(s) ds$$

satisfies the conditions (i)-(iv).

**Example 2.** *If  $f : [0, \infty) \rightarrow [0, \infty)$  non-decreasing, continuous function such that  $f(0) = 0$  and  $f(t) > 0$  for  $t > 0$ , then the operator defined by*

$$O(f; t) = \frac{f(t)}{1 + f(t)}$$

satisfies the conditions (i)-(iv).

**Example 3.** If  $f : [0, \infty) \rightarrow [0, \infty)$  non-decreasing, continuous function such that  $f(0) = 0$  and  $f(t) > 0$  for  $t > 0$ , then the operator defined by

$$O(f; t) = \frac{f(t)}{1 + \ln(1 + f(t))}$$

satisfies the conditions (i)-(iv).

### 3. A COMMON FIXED POINT THEOREM AND IT'S RESULTS

Now, we prove a common fixed point theorem for a family of selfmappings satisfying a general contractive condition of operator type in complete metric spaces.

**Theorem 3.** Let  $(X, d)$  be a complete metric space and  $\{T_\alpha\}_{\alpha \in J}$  be a family of selfmappings of  $X$ . If there exists a fixed  $\beta \in J$  such that for each  $\alpha \in J$ :

$$(3.1) \quad O(f; d(T_\alpha x, T_\beta y)) \leq \lambda O(f; m(x, y))$$

where  $O(\bullet; \cdot) \in \Theta$  and

$$(3.2) \quad m(x, y) = \max \left\{ d(x, y), d(x, T_\alpha x), d(y, T_\beta y), \frac{1}{2} [d(x, T_\beta y) + d(y, T_\alpha x)] \right\}$$

for some  $\lambda = \lambda(\alpha) \in (0, 1)$  and all  $x, y \in X$ , then all  $T_\alpha$  have a unique common fixed point, which is a unique fixed point of each  $T_\alpha$ ,  $\alpha \in J$ .

*Proof.* Let  $\alpha \in J$  and  $x \in X$  be arbitrary. Consider a sequence, defined inductively by

$$x_0 = x, x_{2n+1} = T_\alpha x_{2n}, x_{2n+2} = T_\beta x_{2n+1}, \quad (n \geq 0).$$

For each integer  $n \geq 0$ , from (3.1),

$$(3.3) \quad \begin{aligned} O(f; d(x_{2n+1}, x_{2n+2})) &= O(f; d(T_\alpha x_{2n}, T_\beta x_{2n+1})) \\ &\leq \lambda O(f; m(x_{2n}, x_{2n+1})). \end{aligned}$$

Using (3.2), we have

$$m(x_{2n}, x_{2n+1}) = \max \{d(x_{2n}, x_{2n+1}), d(x_{2n+1}, x_{2n+2})\}.$$

Substituting into (3.3) and (iv), one obtains

$$(3.4) \quad \begin{aligned} O(f; d(x_{2n+1}, x_{2n+2})) &\leq \lambda O(f; \max \{d(x_{2n}, x_{2n+1}), d(x_{2n+1}, x_{2n+2})\}) \\ &= \lambda \max \{O(f; d(x_{2n}, x_{2n+1})), O(f; d(x_{2n+1}, x_{2n+2}))\}. \end{aligned}$$

If  $O(f; d(x_{2n+1}, x_{2n+2})) \geq O(f; d(x_{2n}, x_{2n+1}))$ , then from (3.4) we have

$$O(f; d(x_{2n+1}, x_{2n+2})) \leq \lambda O(f; d(x_{2n+1}, x_{2n+2}))$$

which is a contradiction ( $\lambda < 1$ ). Thus  $O(f; d(x_{2n+1}, x_{2n+2})) < O(f; d(x_{2n}, x_{2n+1}))$  and so from (3.4) one obtains

$$O(f; d(x_{2n+1}, x_{2n+2})) \leq \lambda O(f; d(x_{2n}, x_{2n+1})).$$

Similarly, we get that

$$O(f; d(x_{2n}, x_{2n+1})) \leq \lambda O(f; d(x_{2n-1}, x_{2n})).$$

Thus, for any  $n \geq 1$  we have

$$(3.5) \quad \begin{aligned} O(f; d(x_n, x_{n+1})) &\leq \lambda O(f; d(x_{n-1}, x_n)) \\ &\leq \lambda^2 O(f; d(x_{n-2}, x_{n-1})) \\ &\vdots \\ &\leq \lambda^n O(f; d(x_0, x_1)). \end{aligned}$$

Taking the limit of (3.5), as  $n \rightarrow \infty$ , we have

$$\lim_{n \rightarrow \infty} O(f; d(x_n, x_{n+1})) = 0,$$

which, from (i), implies that

$$\lim_{n \rightarrow \infty} d(x_n, x_{n+1}) = 0.$$

Therefore,  $\{x_n\}$  is Cauchy sequence. (Similarly, see [2]).

Since  $X$  is complete, there is a  $p \in X$  such that

$$\lim_{n \rightarrow \infty} x_n = p.$$

From (3.1) we have,

$$\begin{aligned} O(f; d(x_{2n+1}, T_\beta p)) &= O(f; d(T_\alpha x_{2n}, T_\beta p)) \\ &\leq \lambda \max \left\{ \begin{array}{l} d(x_{2n}, p), d(x_{2n}, T_\alpha x_{2n}), d(p, T_\beta p), \\ \frac{1}{2} [d(x_{2n}, T_\beta p) + d(p, T_\alpha x_{2n})] \end{array} \right\}. \end{aligned}$$

Taking the limit as  $n \rightarrow \infty$  we get

$$O(f; d(p, T_\beta p)) \leq \lambda O(f; d(p, T_\beta p)),$$

which implies that

$$O(f; d(p, T_\beta p)) = 0,$$

which from (i), implies that  $d(p, T_\beta p) = 0$ ; hence  $T_\beta p = p$ .

Now we show that  $p$  is a fixed point of all  $\{T_\alpha\}_{\alpha \in J}$ . Let  $\alpha \in J$  be arbitrary. Then from (3.1) with  $x = y = p = T_\beta p$  we have

$$\begin{aligned} O(f; d(T_\alpha p, p)) &= O(f; d(T_\alpha p, T_\beta p)) \leq \lambda(\alpha) O(f; m(p, p)) \\ &\leq \lambda(\alpha) \max \left\{ \begin{array}{l} O(f; d(p, p)), O(f; d(p, T_\alpha p)), O(f; d(p, T_\beta p)), \\ \frac{1}{2} [O(f; d(p, T_\beta p)) + O(f; d(p, T_\alpha p))] \end{array} \right\} \\ &= \lambda(\alpha) \max \left\{ O(f; d(p, T_\alpha p)), \frac{1}{2} O(f; d(p, T_\alpha p)) \right\}. \end{aligned}$$

Therefore, we get

$$O(f; d(T_\alpha p, p)) \leq \lambda(\alpha) O(f; d(p, T_\alpha p))$$

which implies that

$$O(f; d(T_\alpha p, p)) = 0,$$

which, from (i), implies that  $d(T_\alpha p, p) = 0$  or  $T_\alpha p = p$ . Thus, all  $T_\alpha$  have a common fixed point.

Now we prove the uniqueness of the fixed point  $p$ . Suppose that  $q$  is another a fixed point of  $T_\beta$ . Then it follows, as above, that  $q$  is a common fixed point of all  $\{T_\alpha\}_{\alpha \in J}$ . Thus, from (3.1) we have

$$\begin{aligned} O(f; d(p, q)) &= O(f; d(T_\alpha p, T_\beta q)) \\ &\leq \lambda O(f; m(p, q)) \\ &= \lambda O(f; d(p, q)), \end{aligned}$$

which implies that

$$O(f; d(p, q)) = 0,$$

which, from (i), implies that  $d(p, q) = 0$ . Hence  $p = q$ . Thus,  $p$  is a unique common fixed point of all  $\{T_\alpha\}_{\alpha \in J}$ .  $\square$

**Remark 1.** *It is clear that Theorem 3 is a generalization of Theorem 1 in [2].*

**Remark 2.** *We can have new result, if we combine Theorem 3 and some examples for  $O(f; \cdot)$ .*

**Remark 3.** *Theorem 3 is a generalization of Theorem 1, in fact letting  $f = I$  (identity map) and  $O(f; t) = t$  in (3.1) (it is obvious that  $O(f; \cdot) \in \Theta$ ) one has*

$$d(T_\alpha x, T_\beta y) = O(f; d(T_\alpha x, T_\beta y)) \leq \lambda O(f; m(x, y)) = \lambda m(x, y),$$

*thus Ćirić's [6,7] generalized contraction also satisfies.*

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